

## FNI ECT-106-009-K54 (009E53) IP 20 Module User Manual





1 Notes	
1.1. Manual structure	1.1This manual is organized by organization, so the chapters are
	interconnected.
	Section 2: Basic Security Information.
	Chapter 3: Getting Started Guide
	Chapter 4: Technical Data
1.2. Typography	The following typographic conventions are used in this manual.
	Enumerate The enumeration is displayed as a list with bullets.
	• Headword 1
	• Headword 2
Action	Action descriptions are represented by a front triangle.
	he res lt of the action is represented by an arrow.
	Action description 1
	Action result
	Action description 2
	Step programs can also be displayed numerically in parent eses.
	(1) Step1
	(2) Step2
Grammar number:	
	Decimal numbers are displayed without additional indicator
	s (eg 123)
	Hexadecimal numbers are displayed with an additional indi
	ator hex (eg: 00hex) or with the prefix "OX" (eg: 0x00)
Cross reference	
	Cross-references indicate where to find additional inform
	tion on this topic.
1.3.Symbol -	
·	Notes
	This symbol indicates a general comment.
	Notice!!
	This symbol indicates the most important safety notice.



1.3. Acronym	FNI	FAS network interface
	Ι	Standard input port
	PN	Profinet
	ECT	EtherCAT
	CCIEBS	CC-Link IE Field Basic Slave
	EIP	Ethernet/IP
	EMC	Electromagnetic Compatibility
	FE	Functional ground
	0	Standard output port
1.5.Viewing angle	deviation	Product views and explanations in this manual m
		ay deviate from the actual product. They are on
		ly used left and right to explain the material.

#### 2 Safety

2.1.Expected usage	This manual describes as a decentralized input and output module for connection to an industrial network.
2.2. Install and start	Precautions! Installation and start-up should only be carried out by trained an d specialized personnel. A qualified individual is one who is famili ar with the installation and operation of the product and has the necessary qualifications to do so. Any damage caused by unautho rized operation or illegal and improper use is not covered by the manufacturer's warranty. Equipment operators are responsible for e nsuring compliance with appropriate safety and accident preventio n regulations.
2.3. General security Notes	<ul> <li>Debug and check</li> <li>Before debugging, you should read the contents of the user manu al carefully.</li> <li>The system cannot be used in applications where the safety of pe sonnel depends on the functionality of the equipment.</li> <li>intended use</li> <li>The manufacturer's warranty coverage and limited liability statement do not cover damage caused by: <ul> <li>Unauthorized tampering</li> <li>Improper use</li> <li>Handling, installation and operation that do not conform to the instructions provided in the user manual</li> <li>Owner/Operator Obligations</li> <li>This device is an EMC Class A compliant product. This device gen</li> </ul> </li> </ul>



#### Content

1 Notes	
1.1. Manual structure	3
1.2. Typography	3
1.3. Symbol	3
1.4. Abbreviation	3
1.5. Deviating views	3
2 Safety	
2.1. Intended use	4
2.2. Installation and startup	4
2.3. General Security Notes	4
2.4. Resistance to aggressive substances	4
3 Getting Started Guide	
3.1. Module overview	5
3.2. Mechanical connection	6
3.3. Electrical connections	6
4 Technical data	
4.1. Size	8
4.2. Mechanical data	8
4.3. Operating conditions	8
4.4. Electrical data	8
4.5. Network port	9
	9
5 Integrated	
5.1 Module configuration	1 2
5.2 Data mapping	1 3
5.3 PLC Integration Tutorial	19

6 Appendix



#### 3.1. 模块综述



- **1** Power supply interface
- 2 EtherCAT output port
- 3 DIP switch
- 4 EtherCAT input port
- 5 Module status indicator
- 6 Signal status indicator light
- 7 Sensor power supply+24V
- 8 1-16 Signal interface
- 9 Sensor power supply **OV**
- 10 Sensor power supply+24V
- 11 17-32 Signal interface
- 12 Sensor power supply 0V



LED	display	Function	
PT	blue	EtherCAT protocol	
	close	No error, device initializing	
	Green light flashes 2.5HZ	Pre-operation: The device is in pre-operation	state
X1	Green light flashes1HZ	Safe operation: The equipment is in safe oper-	ation.
	Steady green	Running: The device is running	
	close	No errors, device EtherCAT communication is working	
	Red light flashes 2.5HZ	Invalid configuration	
X2	red light flashing 1HZ	local error	
	red light double flash	Application monitoring timeout	
	Steady green	Device (IN) connected to Ethernet	
L/A1	Yellow light flashes	Device (IN) sends/receives Ethernet frames	
	close	Device (IN) is not connected to Ethernet	
	Steady green	Device (OUT) connected to Ethernet	
L/A2	Yellow light flashes	Device (OUT) sends/receives Ethernet frames	
	closure	Device (OUT) is not connected to Ethernet	
UC	green	Input voltage is normal	
03	Flashing red	Input voltage low (< 18 V)	
	green	Output voltage is normal	
UA	Flashing red	Output voltage low (< 18 V)	
	Red always on	No output voltage present (< 11 V)	



#### **3.1** guide

- 3.2. mechanical connection3. The module is installed with 4 M4 bolts or DIN35 rail clips.
- 3. Electrical connections

#### 3.3.1





2)	Pin		Pin
	1	Tx+	send data+
	2	Rx+	receive data-
	3	Tx-	send data+
	4	Rx-	receive data-

illustrate:

Unused I/O port sockets must be covered with end caps to meet the

IP67 degree of protection. Power port (A-code) 3.3.2

20.000	Pin		Pin
$\bigcirc^3$	1	UA	Actuator Power(BR)
$\bigcirc^4 \bigcirc^2$	2	GND	Actuator Gnd(WH)
	3	US	Bus Power(BU)
	4	GND	Bus Gnd(BK)

1. It is recommended to provide Bus power and Actuator power separately. illustrate: 2. The total current of the Actuator power supply is <4A, and the total current of the Bus power supply is  $\langle 1A;$ 

> 3. The FE connection from the case to the machine must be low impedance and kept as short as possible.

3.3.3



illustrate

1. Input and output signal types support: three-wire PNP, two-wire PNP, dry contact;

2、 Pin +24V single output current maximum 350mA. The total current of the module is <4A;

3. The total current of each 8 channels  $(1^8, 9^16, 17^24, 25^32)$  is <1A;



#### 4.2 mechanical data

Shell material	Aluminum shell
Shell rating conforms to IEC 60529	IP20
power interface	A-Code
input port/output port	Pluggable screw-free quick connect terminals
Size(W*H*D)	136.5mm*92mm*52.7mm
installation type	Screw fixing or DIN35 guide rail snap-or
Weight	about 670g

#### 4.3. Operating conditions

operating temperature	-5° C ~ 80° C
storage temperature	-25°C ~ 85°C

#### 4.4. electrical data

voltage	18~30V DC, symbol EN61131-2
voltage fluctuation	<1%
Operating current at supply voltage 24V	<130mA

#### 4.5 network port

Poet	2 x 10Base-/100Base-Tx
port connection	M12, D-Code
IEEE 802.3 Compliant Cable Type	Shielded twisted pair, min. STP CAT 5/STP CAT 5e
data transfer rate	10/100 M bit/s
cable length	100m
flow control	half working condition/full working condition(IEEE 802.3-PAUSE)



4 Technical data

**4.1.** size







#### 5 integrated

5.1 Module configuration

#### $5.1.1 \, \mathrm{reset}$

When the device is powered off, dial 900;
 Power on the device and wait 10 seconds;
 Power off the device and dial the code to the state before setting;
 Power on the device and restore it to factory status;

#### $5.1.2\ {\rm Node}\ {\rm address}\ {\rm configuration}$

①The node address is assigned by PLC: Dial address X100=4 X10=0 X1=0
②Manual allocation of node address: Dial address X100=4, node number is X10=tens digit X1=units digit

Example:

Dial code: X100=4, X10=2, X1=5 The node number is 25 Note that the maximum node number is 99. After dialing adjustment, you need to power on again;

#### 5.2 data mapping

Digital Output Mapping\_Standard Output 01-08\_3000\_01 :

Digital Output Mapping\_Standard Output 09-16\_6000\_02:

Digital Output Mapping\_Standard Output 17-24\_6000\_03:

Digital Output Mapping\_Standard Output 25-32\_6000\_04:

Digital Input Mapping\_Standard Input 01-08\_3000\_01:

Digital Input Mapping\_Standard Input 09-16\_6000\_02:

Digital Input Mapping\_Standard Input 17-24\_6000\_03:

Digital Input Mapping\_Standard Input 25-32\_6000\_04:

Channel 1<sup>8</sup> output signal mapping Channel 09<sup>16</sup> output signal mapping Channel 17<sup>24</sup> output signal mapping Channel 25<sup>32</sup> output signal mapping Channel 1<sup>8</sup> input signal mapping Channel 09<sup>16</sup> input signal mapping Channel 17<sup>24</sup> input signal mapping Channel 25<sup>32</sup> input signal mapping



5.3 PLC Integration tutorial

5.3.1 Omron NX1P2 Sysmac Studio integrated (ECT)

1. Install the ESI file: Double-click EtherCAT in Configuration and Settings--right-click the main device--select "Show ESI Library", and select the ESI file in the pop-up window for installation.



2、Configure the module into the EtherCAT network: Find the FieldBus Modules in the toolbox on the right. Find the module model icon in the toolbox and double-click to join\_the network.





**3.** PLC goes to online mode, right-click the master device and write the slave device node address

4. Variable mapping: Select the configured node in the  $\rm I/O$  mapping, fill in the name of the variable, and the configuration is completed! .



- 6 appendix
  - 6.1. Order code

Part number	Order code
FNI ECT-106-009-K54	009E53